ECE 313: Electromagnetic Waves

Lecture 5: Continue_ Maxwell's equations

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Gauss Law

• The electric flux passing through any closed surface is equal to the total charge enclosed by that surface.

$$\oint_{S} D_{S} ds = Q , \ Q = \int_{v} \rho_{v} dv$$

• Applying divergence theorem:

$$\oint_{S} D_{S} ds = \int_{v} \nabla D dv = \int_{v} \rho_{v} dv$$

$$\nabla . D = \rho_v$$



Gauss from integral to diff. form:

$$\oint_{S} D_{S} ds = \begin{bmatrix} D_{x}(x + \Delta x, y, z) \Delta y \Delta z - D_{x}(x, y, z) \Delta y \Delta z \end{bmatrix} + \begin{bmatrix} D_{y}(x, y + \Delta y, z) \Delta x \Delta z - D_{y}(x, y, z) \Delta x \Delta z \end{bmatrix} + \begin{bmatrix} D_{z}(x, y, z + \Delta z) \Delta x \Delta y - D_{z}(x, y, z) \Delta x \Delta y \end{bmatrix} = \rho_{v(x, y, z) \Delta x \Delta y \Delta z}$$
Thus

 Δz



$\nabla . D = \rho_v$

Case point charge located outside surface as in Fig.: The number of electric field lines entering the surface equals the number leaving the surface. Therefore, the net electric flux through a closed surface that surrounds no charge is zero.

 $\Delta \Psi = \text{flux crossing } \Delta \mathbf{S} = \mathbf{D}_S \cdot \Delta \mathbf{S}$

The *total* flux passing through the closed surface is obtained by adding the differential contributions crossing each surface element ΔS ,

$$\Psi = \int d\Psi = \oint_{\text{closed}} \mathbf{D}_S \cdot d\mathbf{S}$$

Example

Giving a 60 μ C point charge located at the origin , find the total electric flux passing through that portion of the sphere r=26 cm bounded by $0 \le \theta \le \pi/2$ and $0 \le \varphi \le \pi/2$ Ans: 60/8=7.5 μ C

over all closed surface

$$\oint_{s} D.ds = D * 4\pi r^{2} = 60\mu \rightarrow D = \frac{60\mu}{4\pi r^{2}}$$

over specified surface

$$\Delta \psi = \int_0^{\pi/2} \int_0^{\pi/2} D r^2 \sin \theta d\theta d\phi = \frac{60\mu}{4\pi r^2} r^2 * \frac{\pi}{2} * (-\cos \theta \Big|_0^{\pi/2}) = \frac{60}{8} = 7.5 \mu C$$

Guass' magnetic law





- \circ $\,$ The magnetic field lines are closed
- The magnetic field lines have neither source (start point) or sink (end point)
- It is not possible to have an isolated magnetic poles (or magnetic charges)
- Magnetic field is not a flow source, but a solenoidal source



Maxswell's equations

Differential form	Integral form	
$\nabla \times \overline{E} = -\frac{\partial B}{\partial t}$	$\oint_{c} \bar{E}.dl = -\frac{d}{dt} \int_{s} \bar{B}.ds$	Faraday's law of induction
$\nabla \times \overline{H} = \overline{J} + \frac{\partial D}{\partial t}$	$\oint_{C} \overline{H}.\overline{dl} = \int_{S} \overline{J}.\overline{ds} + \frac{d}{dt} \int_{S} \overline{D}.ds$	Ampere's law
$\nabla . \overline{D} = ho$	$\oint_{S} \overline{D}_{S} ds = \int_{v} \rho_{v} dv$	Gauss flux theorem
$\nabla . \overline{B} = 0$	$\oint_{s} \underline{B} \underline{ds} = 0$	Magnetic flux conservation
$\nabla \underline{J}_{c} = -\frac{d\rho_{v}}{dt}$	$\oint_{s} \underline{J}_{\underline{c}} \cdot \underline{ds} = -\frac{d}{dt} \int_{v} \rho_{v} dv$	Continuity equation

Conservative and solenoidal vector fields

• Conservative field (irrotational): it is the vector field that can be expressed as gradient of other scalar. Line integral of conservative field is path independent. *curl of conservative field=0 (as curl grad=0)*

In electrostatic:

- \overline{E} is a conservative field as $\overline{E} = -\nabla V$, and $\int \overline{E} d\overline{l}$ does not depend on path (it depend on start and end points of integrals), thus closed contour integral (end point same as start point) for conservative field=0. $\oint \overline{E} d\overline{l} = 0$
- V is called potential function of \overline{E} Example: for conservative field $A(\overline{r}) = \nabla (x^2 + y^2)z$ find $\int A(\overline{r}).\overline{dl}$ A (3,-1,4)

$$g_{A} = ((3)^{2} + (-1)^{2})^{4} = 40$$
 $g_{B} = ((-3)^{2} + (0)^{2})(-2) = -18$

$$\int_{C} \vec{A}(\vec{r}) \cdot d\vec{l} = \int_{C} \nabla g(\vec{r}) \cdot d\vec{l} = -18 - 40 = -58$$

Gradient theorem

$$\int_{p}^{q} \nabla \varphi(\mathbf{r}) \cdot d\mathbf{r} = \varphi(\mathbf{q}) - \varphi(\mathbf{p})$$

$$\nabla f = df / dl \hat{a}_{dl} \rightarrow$$
$$\int \nabla f \, dl \hat{a}_{dl} = df = f \, 2 - f \, 1$$

Conservative and solenoidal vector fields

- Every solenoidal vector field can be expressed as the curl of some other vector field.(The curl of any vector field always results in a solenoidal field)
- only solenoidal vector \overline{B} have zero divergence. $\nabla \overline{B} = 0$ Solenoidal field = divergenceless.
- the **surface** integral of **any** and **every** solenoidal vector field across a **closed** surface is equal to zero (since divergence theorem $\int \nabla .\overline{B} dv = \oint \overline{B} . d\overline{s} = 0$)
- In points:
- **1.** Every solenoidal field can be expressed as the curl of some other vector field.
- 2. The curl of **any** and **all** vector fields always results in a solenoidal vector field.
- 3. The surface integral of a solenoidal field across any closed surface is equal to zero.
- 4. The *divergence* of every solenoidal vector field is equal to *zero*.
- 5. The divergence of a vector field is zero **only** if it is **solenoidal**

Curl grad=0 Div curl=0

Example of Conservative and solenoidal vector fields: Electric field in electrostatic and time varying:



In electrostatic Electric field is conservative Vector field



In time varying Electric field produced by changing In magnetic field Is solenoid vector field

If curl of a field is zero it is conservative vector field

If div of a field is zero it is solenoidal vector field



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Potential functions (in time varying fields)

As B is solenoidal vector, a vector magnetic potential A can be defined from B

$$\nabla \overline{B} = 0 \quad \longrightarrow \overline{B} = \nabla \times \overline{A}$$

From faraday's law

$$\nabla \times \overline{E} = -\frac{\partial B}{\partial t} = -\frac{\partial}{\partial t} (\nabla \times \overline{A}) \rightarrow \nabla \times (\overline{E} + \frac{\partial \overline{A}}{\partial t}) = 0$$

$$\overline{E} + \frac{\partial \overline{A}}{\partial t} = -\nabla V, \quad \overline{E} = -\frac{\partial \overline{A}}{\partial t} - \nabla V, \quad \text{in static } \frac{\partial}{\partial t} = 0 \text{ and } \overline{E} = -\nabla V$$

Time varying magnetic field Accumulation of charges
$$\overline{A} = \frac{\mu}{4\pi} \int_{v} \frac{\overline{J}e^{-jKR}}{R} dv \quad V = \frac{1}{4\pi\varepsilon} \int_{v} \frac{\rho e^{-jkR}}{R} dv$$

Potential functions (in time varying fields)

• Non homogeneous wave equation for vector potential A

$$\nabla \times \overline{H} = \left(\frac{1}{\mu} \nabla \times \nabla \times \overline{A}\right) = \frac{\partial \overline{D}}{\partial t} + \overline{J}$$

$$\nabla \times \nabla \times \overline{A} = \mu \varepsilon \frac{\partial \overline{E}}{\partial t} + \mu \overline{J}$$

$$\nabla \times \nabla \times \overline{A} = \mu \varepsilon \frac{\partial}{\partial t} \left(-\nabla V - \frac{\partial \overline{A}}{\partial t}\right) + \mu \overline{J}$$

$$\nabla (\nabla \cdot \overline{A}) - \nabla^2 \overline{A} = -\nabla \left(\mu \varepsilon \frac{\partial V}{\partial t}\right) - \mu \varepsilon \frac{\partial^2 \overline{A}}{\partial t^2} + \mu \overline{J}$$
vector defined by its curl and its divergence

let $\nabla . \overline{A} = -\mu \varepsilon \frac{\partial V}{\partial t}$ *Lorentz condition for potential*



wave equation, its solution represent waves travelling with velocity= $1/\sqrt{\mu\varepsilon}$

Potential functions (in time varying fields)

Non homogeneous wave equation for scalar potential V:



 $\nabla^2 V + k^2 V = -\rho / \varepsilon$

TIME-HARMONIC ELECTROMAGNETICS



The formal procedure for determining the electric and magnetic fields due to time-harmonic charge and current distributions is as follows:[†]

- 1. Find phasors V(R) and A(R) from Eqs. (7-99) and (7-100).
- 2. Find phasors $\mathbf{E}(R) = -\nabla V j\omega \mathbf{A}$ and $\mathbf{B}(R) = \nabla \times \mathbf{A}$.
- 3. Find instantaneous $\mathbf{E}(R, t) = \Re e[\mathbf{E}(R)e^{j\omega t}]$ and $\mathbf{B}(R, t) = \Re e[\mathbf{B}(R)e^{j\omega t}]$ for a cosine reference.

The degree of difficulty of a problem depends on how difficult it is to perform the integrations in Step 1.

Example

In a region where $\mu_R = \epsilon_R = 1$ and $\sigma = 0$, the retarded potentials are given by V = x(z - ct) V and $\mathbf{A} = x[(z/c) - t]\mathbf{a}_z$ Wb/m, where $c = 1/\sqrt{\mu_0\epsilon_0}$. a) Show that $\nabla \cdot \mathbf{A} = -\mu \epsilon (\partial V / \partial t)$: *Near field:* Propagation does not appear First, through A and V it appears $\nabla \cdot \mathbf{A} = \frac{\partial A_z}{\partial z} = \frac{x}{c} = x \sqrt{\mu_0 \epsilon_0}$ In E and H it is along z E along x Second, B along y $\frac{\partial V}{\partial t} = -cx = -\frac{x}{\sqrt{\mu_0 \epsilon_0}}$ E not as same direction of A since it depend on both grad V and A -in far field E will depend on A only) b) Find **B**, **H**, **E**, and **D**: Use $\mathbf{B} = \nabla \times \mathbf{A} = -\frac{\partial A_x}{\partial x} \mathbf{a}_y = \left(t - \frac{z}{c}\right) \mathbf{a}_y \mathbf{T}$ Then $\mathbf{H} = \frac{\mathbf{B}}{\mu_0} = \frac{1}{\mu_0} \left(t - \frac{z}{c} \right) \mathbf{a}_y \, \mathrm{A/m}$ Now,

$$\mathbf{E} = -\nabla V - \frac{\partial \mathbf{A}}{\partial t} = -(z - ct)\mathbf{a}_x - x\mathbf{a}_z + x\mathbf{a}_z = \underline{(ct - z)\mathbf{a}_x \, \mathrm{V/m}}$$

Then

 $\mathbf{D} = \epsilon_0 \mathbf{E} = \frac{\epsilon_0 (ct - z) \mathbf{a}_x \text{ C/m}^2}{\epsilon_0 (ct - z) \mathbf{a}_x \text{ C/m}^2}$